

## CHAPTER

PART-4

1.

## Transformer.

### Introduction.

- A Transformer is a static device that Transfer energy from one circuit to another circuit through medium of magnetic field and without change in frequency.
- winding which are connected to the power supply is known as Primary winding.
- winding which are connected to the Load is known as Secondary winding.
- both winding are electrically isolated but magnetic coupled.

### Construction.

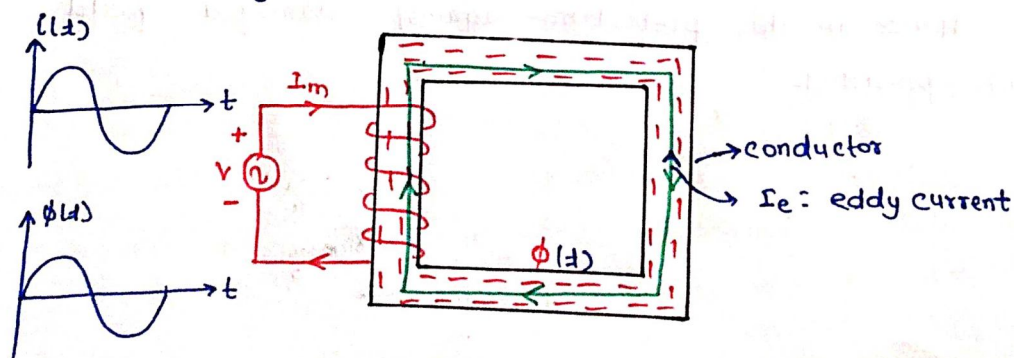
#### (i) core :-

- It is used to provide Low reluctance path to the field.
- Silicon is added in steel in order to increase the resistivity of material and permeability also increases & magnetostiction decreases.

Resistivity  $\uparrow$ , Permeability  $\uparrow$ , magne to striction  $\downarrow$ .

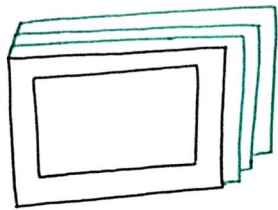
CRGROSS :- Cold Rolled Grain oriented silicon steel.

- Permeability  $\uparrow$
- Hysteresis & eddy current loss  $\downarrow$
- rolling is done in the direction of magnetization.



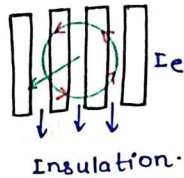
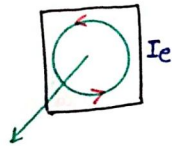


- In order to provide low reluctance, core should be made up of magnetic material such as steel, which is also conductor.
- when flux linkage changes with steel (i.e. core) so there is an induced emf and current flows which is known as eddy current. The losses due to this is known as eddy current loss.
- By addition of silicon in steel, resistivity increases hence eddy current decreases.
- Lamination are done in order to reduce eddy current loss.

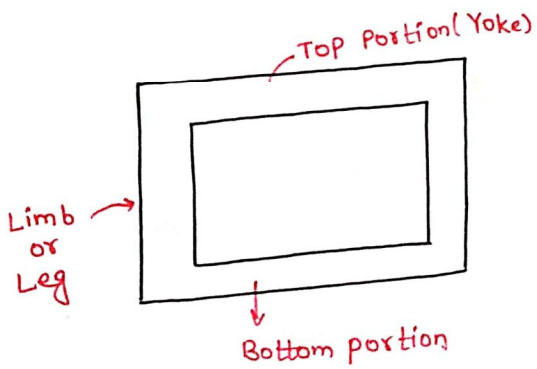


- Lamination are isolated using coating of varnish.

Cross sectional view of core.

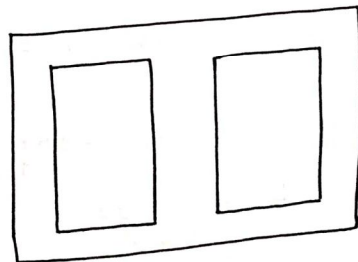
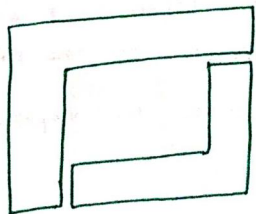


- Eddy current loss reduces by using insulation.



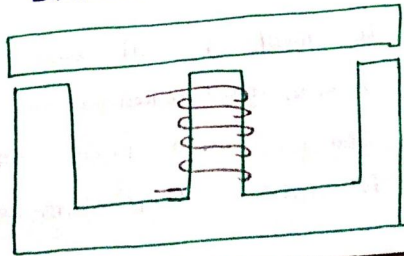
Two Legged core.

- made up of L shape laminations.



Three Legged core.

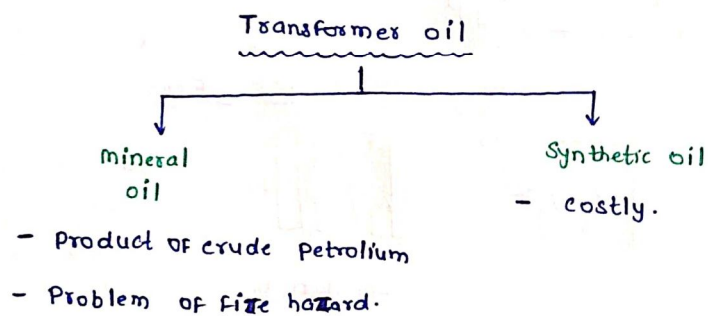
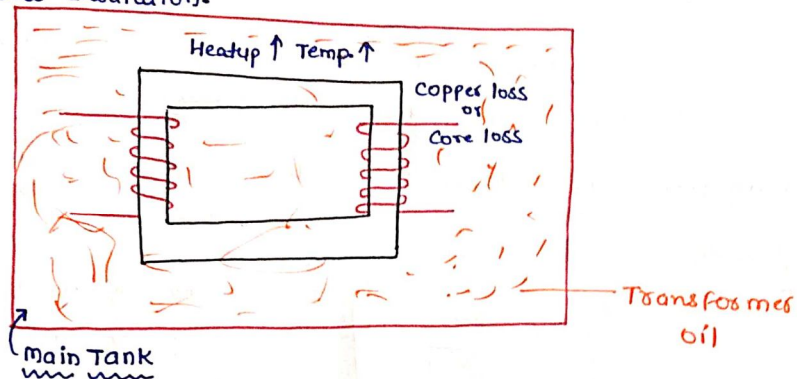
- Made up of E & I shaped lamination.



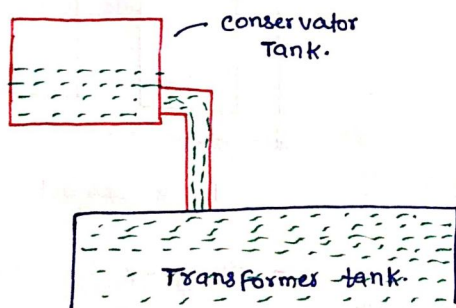


(ii) winding :- made up of solid or standard copper or Aluminium Conductors.

(iii) Transformer oil :- Due to copper loss & core loss, winding and core heat up. Hence temp. increases. So, T.F oil used, which act as coolant as well as ~~main~~ insulation.



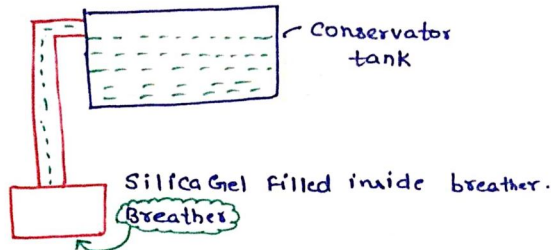
(iv) Conservator tank or Expansion tank



- The level of oil, also when Load changes, when Load increases, oil expands and when Load decreases, oil contracts so the oil level changes with Load hence conservator tank or expansion tank is used to keep main tank full of oil.



(V) Breather



- when temp. increases, the oil expands. the gas at the top of the oil level expelled out. when temp. decreases, the oil contracts. so it will draw air from out side. This air may contain moisture. So breather is used to restrict moisture, which consist of silica gel.

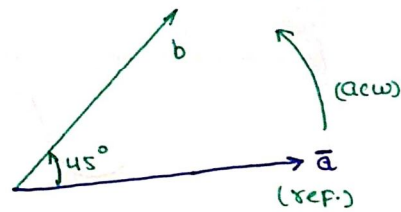
(6) Bucholz relay

- It is used to detect internal fault of Transformer.
- It is connected in between conservator tank and main tank.
- when fault occurs, the temperature increases, the oil decomposed into gaseous bubbles. These gaseous bubble moves from main tank to conservator tank through bucholz relay. These gaseous bubbles disturb mercury float. So mercury float send signal to Alarm and circuit Breaker.

Phasors :-

i)  $\bar{a}$   $\bar{b}$

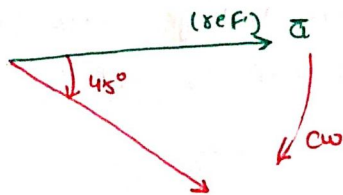
$$\bar{a} = a \angle 0^\circ, \bar{b} = b \angle +45^\circ$$



-  $\bar{b}$  lead  $\bar{a}$  by  $45^\circ$

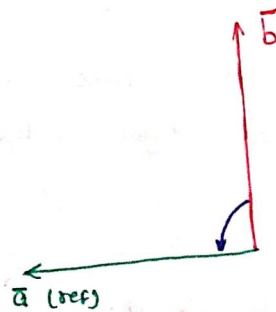
-  $\bar{a}$  lag  $\bar{b}$  by  $45^\circ$

ii)  $\bar{a} = a \angle 0^\circ, \bar{b} = b \angle -45^\circ$



-  $\bar{b}$  lags  $\bar{a}$  by  $45^\circ$

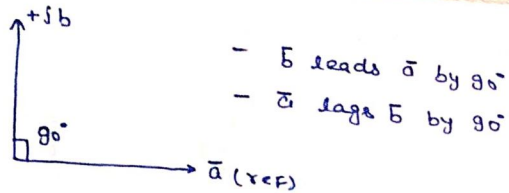
iii)



-  $\bar{b}$  lags  $\bar{a}$  by  $90^\circ$

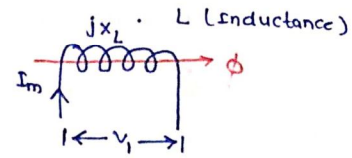
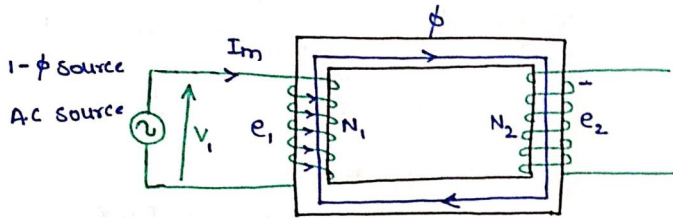


(iv)  $\bar{a} = a \angle 0$  (REF)  $j = +90^\circ$   
 $\bar{b} = jb$   
 $= b \angle +90^\circ$



$j = 90^\circ$   
 $1/j = -j = -90^\circ$

Induced EMF in Transformer :-

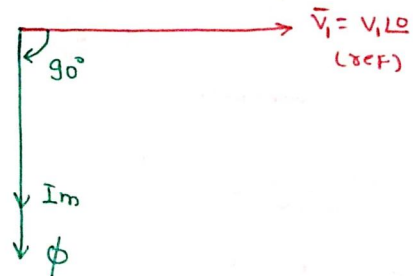
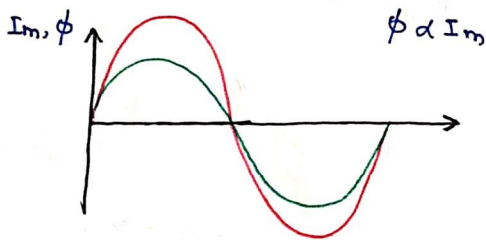


$\bar{I}_m = \frac{V_1 \angle 0}{jX_L} = \frac{-|V_1|}{|X_L|} \angle -90^\circ$

$I_m$  = magnetizing current.

- magnetizing current ~~is~~ lags supply voltage by  $90^\circ$

$I_m$  lags  $V_1$  by  $90^\circ$



$\phi$  = space-phasor

$\phi \propto I_m$

$I$  = time-phasor

$I_m = I_{max} \sin \omega t$

$\phi = \phi_{max} \sin \omega t$

- AS Flux is time varying so when Flux linkage with coil (1) and coil (2) changes so there is an induced emf  $e_1$  and  $e_2$ .

$\phi = \phi_m \sin \omega t$   
 $\downarrow$   
 peak value.

$e_1 = -N_1 \frac{d\phi}{dt}$

$e_2 = -N_2 \frac{d\phi}{dt}$



$$e_1 = -N_1 \frac{d}{dt} (\phi_m \sin \omega t)$$

$$e_2 = -N_2 \frac{d}{dt} (\phi_m \sin \omega t)$$

$$e_1 = -N_1 \phi_m \omega \cos \omega t$$

$$e_2 = -N_2 \phi_m \omega \cos \omega t$$

$$e_1 = -N_1 \phi_m \omega \sin(90^\circ - \omega t)$$

$$e_2 = -N_2 \phi_m \omega \sin(90^\circ - \omega t)$$

$$e_1 = N_1 \phi_m \omega \sin(\omega t - 90^\circ)$$

$$e_2 = N_2 \phi_m \omega \sin(\omega t - 90^\circ)$$

but  $\phi = \phi_m \sin \omega t$

- both  $e_1$  &  $e_2$  lags  $\phi$  by  $90^\circ$ .

$$E_1 = N_1 \phi_m \omega \sin(\omega t - 90^\circ)$$

$$E_2 = N_2 \phi_m \omega \sin(\omega t - 90^\circ)$$

$$e_1 = E_{m1} \sin(\omega t - 90^\circ)$$

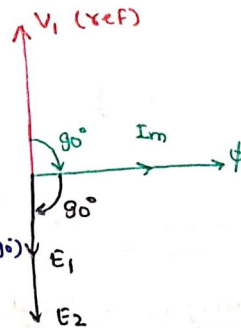
$$e_2 = E_{m2} \sin(\omega t - 90^\circ)$$

$$E_{m1} = N_1 \phi_m \omega$$

$$E_{m2} = N_2 \phi_m \omega$$

$$E_{m1} = 2\pi f N_1 \phi_m$$

$$E_{m2} = 2\pi f N_2 \phi_m$$



Rms Value :-  $E_1 = \frac{E_{m1}}{\sqrt{2}} = \frac{\sqrt{2} \pi f N_1 \phi_m}{\sqrt{2}}$

$$E_2 = \frac{E_{m2}}{\sqrt{2}} = \frac{\sqrt{2} \pi f N_2 \phi_m}{\sqrt{2}}$$

$$E_1 = 4.44 f \phi_m N_1$$

Imp. result

$$E_2 = 4.44 f \phi_m N_2$$

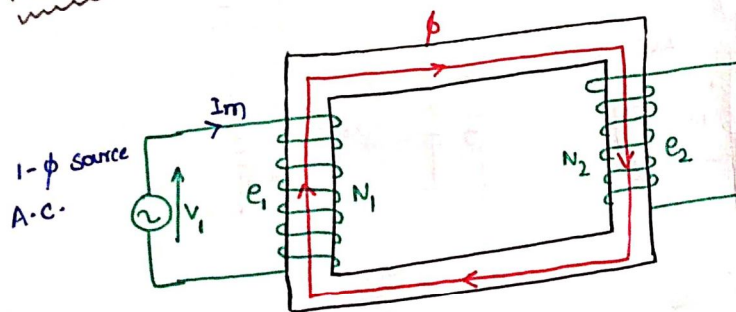
Imp. result.

$$\frac{E_2}{E_1} = \frac{N_2}{N_1} = K = \text{Transformation Ratio.}$$

Imp. Result.

$$a = \frac{N_1}{N_2} \text{ turns Ratio}$$

Part - 5



$$V \approx E_1 = 4.44 f \phi_m N$$

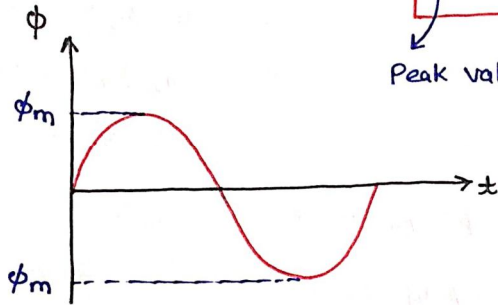
If voltage drop of primary winding is neglected.



$$\phi_m \approx \frac{V_1}{4.44 f N_1}$$

$$\phi_m \propto \frac{V_1}{f}$$

Ratio of Supply voltage and frequency.



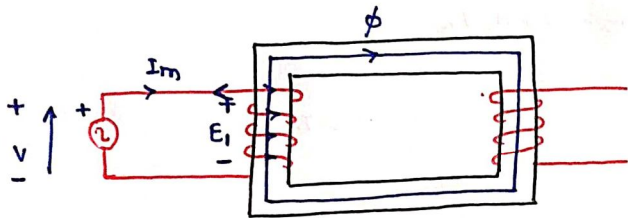
Peak value of Flux.

- IF ratio of supply voltage & frequency remains constant, so  $\phi_m$  (i.e. peak of flux) remains constant.

Part-5

Polarity of Induced Emf

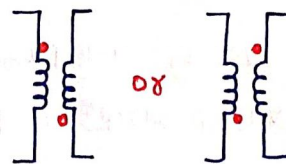
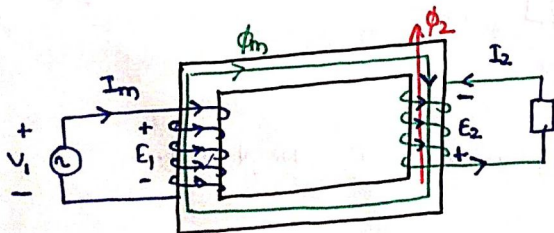
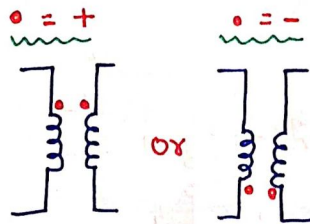
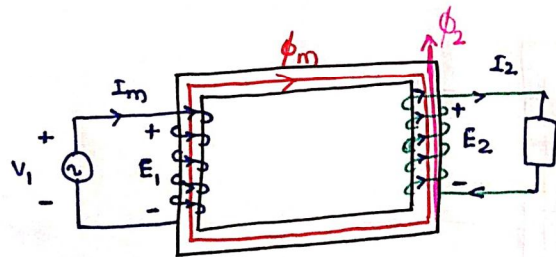
Polarity of induced emf  $E_1$  :-



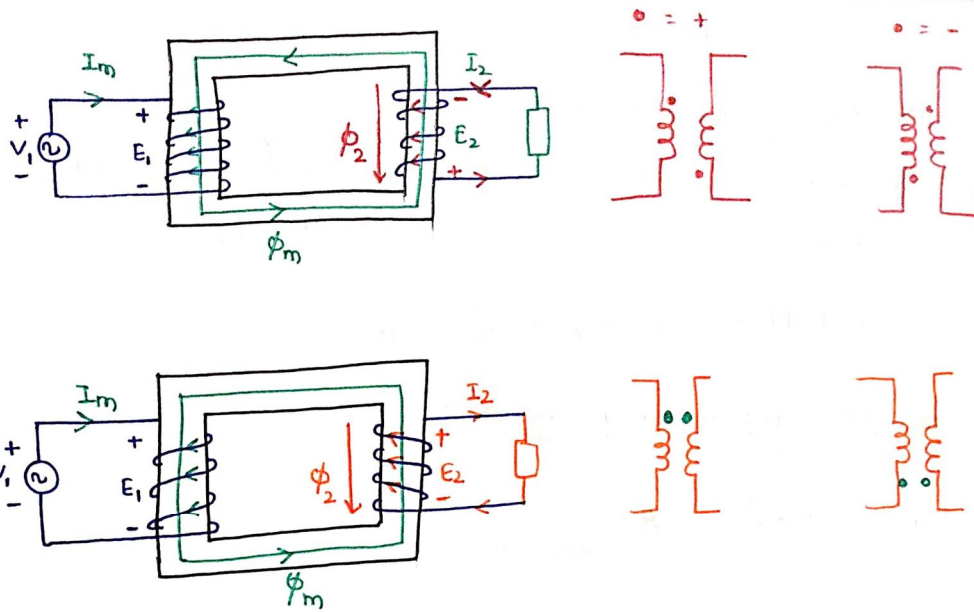
Primary winding.

- when time varying flux links with primary winding, there is an induced emf in coil (1). According to Lenz's Law, the polarity of induced emf  $E_1$  such that, if current would flow due to  $E_1$ , it should oppose the  $I_m$  current.

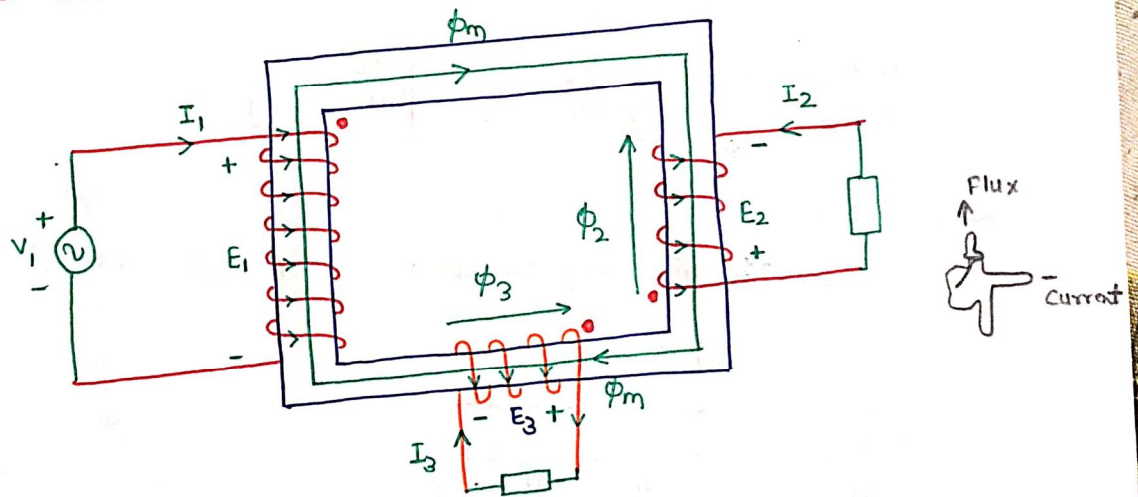
Polarity of induced emf  $E_2$  :-



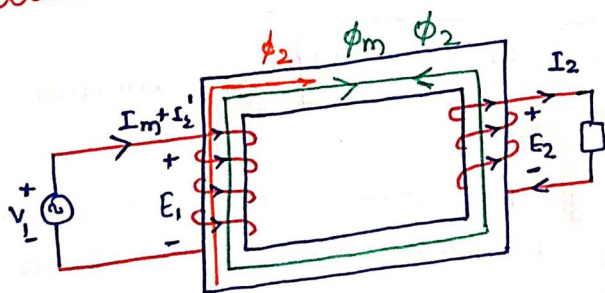




Three phase winding Dot Conversion :-



Transformer on Load :-



- when Transformer ON No Load.

$\Phi_m \propto V/f$  (supply)  
Net Flux in core =  $\Phi_m$ .

- When  $\Phi_m$  Flux interacts with coil (2), an induced emf  $E_2$  & IF Load connected to coil (2)  $I_2$  current flows, A/c to Lenz's Law  $\Phi_2$  Flux Produced by  $I_2$  should oppose  $\Phi_m$ .  
Net Flux in core =  $\Phi_m - \Phi_2$



↓ Net flux in core =  $\phi_m - \phi_2$

but  $\phi_m \propto V/f$  (source).

- To keep net flux in core constant ( $\phi_m$ ), (coil 1)/ source draws additional current  $I_2'$  from source, which produces flux  $\phi_2$

$$\text{Net Flux} = \phi_m - \cancel{\phi_2} + \phi_2 = \phi_m$$

Source current / Primary winding current :-

$$I_1 = I_m + I_2' \quad \phi = \frac{\text{MMF}}{\text{Reluctance}}$$

$$\phi_2 = \frac{N_1 I_2'}{\text{Reluctance}}, \quad \phi_2 = \frac{N_2 I_2}{\text{Reluctance}}$$

$$\frac{N_1 I_2'}{\text{Reluctance}} = \frac{N_2 I_2}{\text{Reluctance}}$$

$$\frac{N_2}{N_1} = \frac{I_2'}{I_2}$$

as  $I_1 = I_m + I_2'$

as  $I_m$  current is very small in comparison to  $I_2'$ .

$$I_1 \approx I_2'$$

$$\frac{N_2}{N_1} = \frac{I_1}{I_2} = \frac{V_2}{V_1} = \frac{E_2}{E_1} = K$$

$$V_1 I_1 = V_2 I_2$$

$$\text{KVA of primary} = \text{KVA of secondary}$$

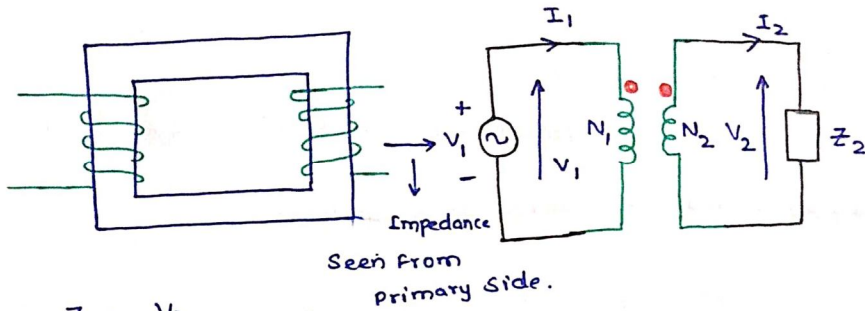
Approximation.

- Load current is always greater than primary magnetizing current. only fault current is greater than load current in electrical world.

$$\text{fault current} > \text{Load current} \gg \text{magnetizing current.}$$



## Impedance Transformation :-



$$Z_2 = \frac{V_2}{I_2}$$

Impedance Seen from primary side.

$$= \frac{V_1}{I_1}$$

$$\frac{V_2}{V_1} = \frac{N_2}{N_1} = \frac{I_1}{I_2}$$

$$V_1 = \frac{N_1}{N_2} V_2, \quad I_1 = \frac{I_2 N_2}{N_1}$$

$$\frac{V_1}{I_1} = \frac{N_1 V_2 \times N_1}{N_2 \times I_2 \times N_2} = \left(\frac{N_1}{N_2}\right)^2 \frac{V_2}{I_2} = \frac{Z_2}{K^2} \quad \therefore \frac{N_2}{N_1} = K \quad \frac{N_1}{N_2} = \frac{1}{K}$$

\*\*\*  
 Impedance  
 Seen from Primary side =  $\frac{Z_2}{K^2} = Z_2' =$  Secondary refer. to primary side.

If  $Z_1 =$  Primary Impedance.

Primary impedance refer to secondary ( $Z_1'$ )

$$*** \quad Z_1' = Z_1 \times K^2 = Z_1 \times \left(\frac{N_2}{N_1}\right)^2 = Z_1 \left(\frac{V_2}{V_1}\right)^2$$

$$\bar{Z} = R, \quad Z = jX_L, \quad \bar{Z} = -jX_C$$

Trick :-

$$Z_2' = Z_2 \times \left(\frac{V_1}{V_2}\right)^2$$

$$Z_1 \times \left(\frac{V_2}{V_1}\right)^2$$